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by
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The Laboratory for Applications of Remote Sensing

**Purdue University
Lafayette, Indiana**

Final Report
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LARS/Purdue - IBM Houston Scientific Center
Joint Study Program
by
P. E. Anuta¹, E. M. Rodd², R. E. Jensen²
and P. R. Tobias²

I. Summary

This report describes work performed during the second part of the LARS/IBM HSC Joint Study program which began April 1, 1971 and terminated April 1, 1972. Work during the first part of the study ending November 30, 1971 concentrated on analysis of the HSC vidicon film scanning system. Included was a comparison of data derived from this system and the LARS/U. of Michigan airborne multispectral scanner system. Comparison of vidicon digitized film and film digitized on a rotating drum microdensitometer was also included. This work is reported in IBM Publication No. 320.2421 "First Interim Progress Report for IBM Houston Scientific Center/LARS - Purdue Joint Study Program." The second part of the study consisted of development of a closed boundary finding algorithm by IBM and its evaluation by LARS. The purpose of the algorithm is to enable automatic determination of boundaries, such as agricultural

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field boundaries, in digitized aerial or satellite imagery. The algorithm is described and a pictorial evaluation is presented in this report.

II. Field Selection in Digital Images

One of the major problems in the development of automatic pattern recognition systems for earth resources image data is the delineation of closed boundaries around homogeneous areas containing a material of interest. Identification of these closed areas allows categorization of all the enclosed image elements by group pattern recognition techniques. The reliability and speed of the pattern recognition process is markedly increased when groups, i.e., fields, of samples are used. If the fields are not known each image element in the data must be classified separately which is very time consuming and less accurate. Thus, closed boundary finding methods are being widely studied as part of earth resources data analysis research.

Recent work reported by Rosenfield¹ and Anuta² approached the boundary finding problem using the picture gradient which spatially differentiates the data and produces an edge picture. The problem with this approach is that the gradient is inherently "noisy" and produces borders which are discontinuous, of varying width, and the output also consists of many isolated spurious border points. A more stable and lower noise approach using clustering is reported by Wacker.³ The quality of his boundary output is high; however, the algorithm is very time consuming and closed boundaries are not guaranteed. The boundary finding algorithm reported here guarantees closure and is relatively fast. The algorithm description which follows is extracted from an IBM report by Rodd⁴ who developed the program.

III Closed Boundary Finding Algorithm (CBA)

In the following discussion each point of a digital picture is called a pixel (picture element) and a group of points is called a pixel group. In the implementation, pixel groups are squares of g pixels on a side and thus have g^2 pixels in each group. A field is a collection of pixel groups which have been found to come from the same statistical distribution. The algorithm proceeds by computing statistics for a pixel group and comparing them to the statistics of existing sets of pixel groups using the t - test⁵. The t - test is used to determine whether two adjacent groups came from the same distribution and thus from the same field.

1. Statistical Method

Before describing the geometry of building fields using more than one spectral range we describe the statistical method used when comparing two samples. The t -test is used to compare a pixel group which has not been classified as part of a field with some other pixel group or set of pixel groups which form a defined field. The formulas used make two assumptions about the population formed by the pixels: (1) the populations of all fields are normal and (2) the populations of all fields have the same variance.

Call the unclassified pixel group sample 1 and the collection of one or more pixel groups which are classified sample 2. The goal is to compute a value of t to compare against a critical value to determine if the two samples are from a single population (i.e. determine if the pixel group is part of the same field as sample 2).

Let:

x_{ij} be pixel i of sample j ,

\bar{x}_j be the mean of sample j ,

x_{ij} be $(x_{ij} - \bar{x}_j)$,

n_j be the number of pixels in sample j .

Note that $N_j = g^2$ if only one pixel group is considered.

First compute the pooled estimate of variance.

$$s_p^2 = \frac{\sum_i x_{i1}^2 + \sum_i x_{i2}^2}{(n_1-1) + (n_2-1)}$$

Note that the $\sum_i x_{ij}^2$ is computed as usual by

$$\sum_i x_{ij}^2 = \frac{n_j \sum_i x_{ij} - (\sum_i x_{ij})^2}{n_j}$$

Now the value of t is:

$$t = \frac{\bar{x}_1 - \bar{x}_2}{\sqrt{s_p^2 \left(\frac{1}{n_1} + \frac{1}{n_2} \right)}}$$

A two-tailed test is used with the number of degrees of freedom equal to $(n_1 - 1) + (n_2 - 1)$.

Occasionally a single pixel group will contain pixels from two areas with radically different values of \bar{x}_j or will contain mostly pixels from say a darker area and one or more pixels from an extremely bright area such as a road or a house with a white roof. This will make s_p^2 very large and consequently make t very small thus confirming the null hypothesis that the two samples are

from the same field. Actually this is not the case for sample 1 does not belong with any other pixel groups. In fact, if sample 1 is included in the field with sample 2, any further computations of t using the field with samples 1 and 2 now combined into a single field will produce a large s_p^2 and small t and an acceptance of the null hypothesis. What has really happened is that sample 1 violates assumption 2. To avoid the problem it is necessary to compute the standard deviations σ_1 and σ_2 and if either is greater than some empirical constant times the appropriate \bar{X}_j , the null hypothesis is rejected.

2. Building of Fields

The picture is processed one row of pixel groups at a time. First the field building algorithm will be described in terms of processing a picture of one spectral band. Before processing starts on a row of pixel groups, the sums of the elements and sums of the squares of the elements of each pixel group in the row are computed. The pixel groups are numbered left to right so that s_1 is the sum of elements of the leftmost pixel group in the row and q_1 is the sum of the squares of the elements of the leftmost pixel group. There are W pixel groups in a row.

The k 'th group of the row of pixel groups being processed will be designated as group k . The first group in the current row is thus group 1. The field to which group k is assigned is given by f_k . The k 'th pixel group in the previous row of pixel groups is designated as group (k) . The first such group is group (1) . The field to which group (k) is assigned is given by $(f)_k$.

The first row is easiest to process. Group 1 is arbitrarily assigned to field 1 and field 1 is noted as containing one pixel

group. Letting S_n be equal to the sum of the pixels in field n and Q_n be equal to the sum of squares of pixels in field n , then S_1 is equal to s_1 and Q_1 is equal to q_1 .

Now group 2 is compared to group 1 (group 1 is sample 2 and group 2 is sample 1). If the null hypothesis is accepted, group 2 is added to field 1. Adding to field 1 means noting that field 1 now has 2 pixel groups and

$$S_1 = S_1 + s_2$$

$$Q_1 = Q_1 + q_2.$$

If the null hypothesis is rejected, then group 2 is assigned to field 2 and field 2 is noted as containing one pixel group and

$$S_2 = s_2$$

$$Q_2 = q_2.$$

Next group 3 is compared to group 2 and in general group k is compared to group $k-1$ until the end of the row is reached.

The second row and all succeeding rows are processed by the following steps.

(a) Group 1 is compared to the field containing group (1). Two possibilities exist. Either the null hypothesis is accepted and group 1 is considered part of field $(f)_1$ or the null hypothesis is rejected and group 1 is different.

If they are the same (i.e. group 1 is part of field $(f)_1$), group 1 is added to field $(f)_1$. Adding means noting that field $(f)_1$ has one more pixel group and

$$S(f)_1 = S(f)_1 + s_1$$

$$Q(f)_1 = Q(f)_1 + q_1.$$

Note that $S(f)_1$ means the $(f)_1$ 'th element of S where $(f)_1$ is the field to which group (1), the first group on the previous row, was assigned.

If they are different processing continues to group 2.

(b) Group 2 through $W-1$ are processed in the same manner. Group k is compared to the field which contains group (k) .

If they are the same, group k is added to field $(f)_k$. Then a check is made to see if group $k-1$ has been assigned to a field. If so processing continues to group $k+1$. If not, group $k-1$ is compared to field f_k (which is the same as $(f)_k$). If they are different, processing continues to group $k+1$. If they are the same, group $k-1$ is added to field f_k and then a check is made to see if group $k-2$ has been assigned to a field and so on.

If they (group k and field $(f)_k$) are different a check is made to see if group $k-1$ has been assigned to a field. If not, processing moves to group $k+1$. If so, group k is compared to field f_{k-1} . If they are the same group k is added to field f_{k-1} . If not, processing continues to group $k+1$.

(c) Group W is processed just like groups 2 through $W-1$ except that upon termination of processing of group W , there is no group $k+1$ to begin processing.

(d) After group W is processed, a second pass of the row is made, this one backwards across the row. The pass starts at group W . When a group k is encountered which has not been assigned to a field, group k is assigned to a new field. Then

if group $k-1$ is unassigned, it is compared to group k . If they are the same, group $k-1$ is added to field f_k and group $k-2$ is checked to see if it is unassigned and so forth. Whenever group $k-j$ is unassigned but different from the field which contains groups k through $k-j+1$, then group $k-j$ is assigned to a new field and a check is made to see if group $k-j-1$ is assigned and so forth. Whenever group $k-j$ is already assigned, scanning continues for unassigned groups.

To handle multi-spectral data, a vector S , a vector Q , a vector s and a vector q must be maintained for each spectral band. When two samples are compared, a t is computed for each spectral band. If the null hypothesis is rejected on the basis of the value of t for any spectral band, then the samples are different.

IV. Implementation

The algorithm has been implemented on System/360 under CP-67/CMS. The program is written in FORTRAN with the exception of assembly language subroutines for input data conversion and for timing. The data for each channel are on a separate file on secondary storage. The data files are sequential with each record containing one row of pixels. It is simple to adapt to some other format of raw data because all input of pixel data is done from a single subroutine.

The following parameters are input to the program:

1. The value of g , the number of pixels on one side of a pixel group.
2. Those rows and columns of the picture which are to be processed.

3. The significance level to be used for the t-test. Four values are available.
4. The number of channels to be processed.

The program can process any number of rows of pixels on a single run. The number of columns is limited by the dimensions of certain variables. Thus, the program is designed to process pictures which are long strips.

Output is to a line printer. Results for the first 50 rows of pixel groups are printed after the first 100 rows are processed and results for the next 50 rows printed after another 50 rows have been processed and so forth. On the output, each field is assigned a character. Only the boundaries of each field are printed. The program is **intended to be used** with a per field classification program so that when a field is closed (closed means that no pixel groups in the current row of pixel groups belong to that field), the classification program is invoked to classify the closed field as corn etc. Also before printing, any fields in the last row to be printed which are still open need to be classified.

Note that the maximum number of fields which can be open at one time is twice the number of pixel groups in a row. Thus the vectors S and Q need have only $2W$ elements since each time a field is closed, those elements of S and Q which contained the information concerning the field just closed can be released for use by a new field.

A source listing for the program modified to work on the IBM System 360 44PS operating system is included in Appendix I. A discussion of the input data and the program is supplied in Appendix II.

V. Evaluation of the CBA

In order to analyze the performance of the closed boundary finding algorithm the program was applied to two remote sensor data sets. The primary application was to aircraft multispectral scanner data from flights over agricultural areas in Indiana. Regions such as this contain a uniform checkerboard pattern of rectangular fields oriented generally in a north-south direction. Imagery gathered over this area using north-south flight paths will contain a field boundary structure which is colinear with the X-Y axes of the imagery. These conditions make data of this type ideal for testing boundary finding algorithms due to the predictability of the scene border structure. A 1 mile by 8 mile strip of this agricultural scanner data was used to test the CBA using a variety of parameter values for the algorithm.

The CBA was also applied to a second data set to observe the behavior of the algorithm on irregular and randomly shaped features in the imagery. The data set is from a flight over Yellowstone National Park, Wyoming, and contains meadow, forest, rock outcrops and other irregular features.

These test cases are presented as examples to show the typical performance to be expected from the algorithm for these image context categories. The evaluation method is strictly subjective since no reference standard or qualitative evaluation method exists for testing

the boundary results. Field by field visual analysis enables a reasonable judgement to be made as to the quality and consistency of the closed fields the algorithm is finding. Thus, gray scale pictorial printouts and the corresponding closed boundary finding algorithm printouts having the same scale are presented in figure form for documentation and evaluation purposes in this report.

A typical CBA result is presented in Figure 1. A gray scale pictorial computer printout is presented in Figure 1a for a strip of data in the .58 - .65 micrometer band of typical Indiana farm land. This image was generated using a set of 10 print chain characters which reproduce an approximation of a gray scale. The CBA output in Figure 1b was generated using the following parameter values: Minimum points per field = 128; Significance level = 4; Channels = 4,6,8; Pixel group size = 2 by 2. It is difficult to visually evaluate the results on a large scale. Individual fields must be selected in the gray scale printout and the corresponding area located in the CBA output. Inspection of many fields in this manner reveals that the basic border structure of the scene is being captured and in general each field in the gray scale tends to be broken up into two or more subfields. A fixed sequence of symbols is used to represent the closed boundaries and the sequence is repeated as the set of available symbols is exhausted. It is assumed to be desirable to have too many fields defined rather than too few since then there will be less chance of a CBA field covering more than one real field. Also it is entirely reasonable to expect that real fields will contain variabilities which translate to separate sub-fields when observed spectrally.

In order to evaluate the sensitivity of the CBA to variations in the program parameters several figures were generated from CBA output for visual comparison. The minimum number of points allowable for a field is moderately influential in determining the nature of the border output. In Figure 2 three values for MINFLD are illustrated. The difference between MINFLD of 32 and 64 is not great; however, sharper and more linear borders are obtained for MINFLD = 128. The minimum field of 128 picture elements corresponds to 2.4 acres for the scale of this data. Larger minimums may be desirable if the average size of the sub-fields in the scene is larger than this figure. Next, the significance level was varied and Figure 3 contains output for SIGLEV of 2, 3 and 4. It is apparent that this parameter has the strongest effect on the CBA output. For values of 2 and 3 a great deal of border structure is lost and it is assumed that for this scene and three channel operation significance level 4 is the more desirable value to use.

The CBA was originally written to use one channel only to derive borders. The program was expanded to utilize multiple channels and the three channels used (4, 6, 8) tended to give the best results. These channels cover the .52 - .57 (green), .58 - .65 (red) and .72 - .92 (infrared) portions of the spectrum, respectively. These channels tend to be less cross correlated than other combinations of three thus contain more picture information than would channels demonstrating more correlation. Use of more than three channels tended to produce an excess of borders and the output was judged to be degraded. The comparison presented in Figure 4 is for a one-channel versus a three-channel run. It is apparent that a certain amount

of the horizontal border is lost while the vertical border structure appears to be captured relatively well.

These results tended to indicate that it is desirable to use multiple channels for border finding. This approach requires additional computation and the problem of selecting which channels to use is compounded. These considerations led to the decision to test the usefulness of the principal components transformations [6] in the border finding process. This transformation is linear and its effect is to concentrate the variance in the multiple image set in a minimum number of channels. The first principal component is an image channel formed as a linear combination of all original channels such that in this case approximately 75% of the variance in the image set is contained in it. The second principal component contains 12% of the variance, the third 7% and the rest the remaining variance on a decreasing scale. The possible advantages to using the principal components are that fewer channels may suffice and it eliminates the uncertainty of which channels to use.

The principal component transform was performed on the data set which was used to produce the previous output. The CBA was run on the transformed data using the first principal component in one case and the first three in a second case. The results of the runs are displayed in Figure 5 along with the three channel results from Figure 1. Again it is evident that the single channel result tends to miss horizontal boundaries as was observed for the single channel unaltered data. The three component results tend to agree with the

reference case. From this it was concluded that the principal component approach would simplify channel selection but more than one channel would still be required for processing.

The CBA was applied to one other data set obtained from an aircraft scanner flight over Yellowstone National Park, Wyoming, in 1967. A gray scale printout of the .52 - .55 micrometer band of the scanner data is presented in Figure 6. The same parameter values used for previous runs were used for the CBA and the output is pictured on the right in Figure 6. The elongated areas of meadow and rocky material are bordered reasonably well in the center and lower part of the area. The upper area contains forest stands and it is extremely difficult to evaluate what the CBA is doing here. Detailed evaluation of the performance for this scene is beyond the scope of this report and this evidence is presented as an example only.

VI Summary

A closed boundary finding algorithm is described which attempts to extract border information from digitized multispectral imagery. The algorithm was applied to multispectral aircraft scanner data from agricultural and wildland scenes to evaluate its performance. Visual evaluation of results indicate reasonably good performance in the agricultural scene; however, precise evaluation was not possible within the scope of this study. Subjective evaluation of performance for the wildlands case was more difficult than for the agricultural case.

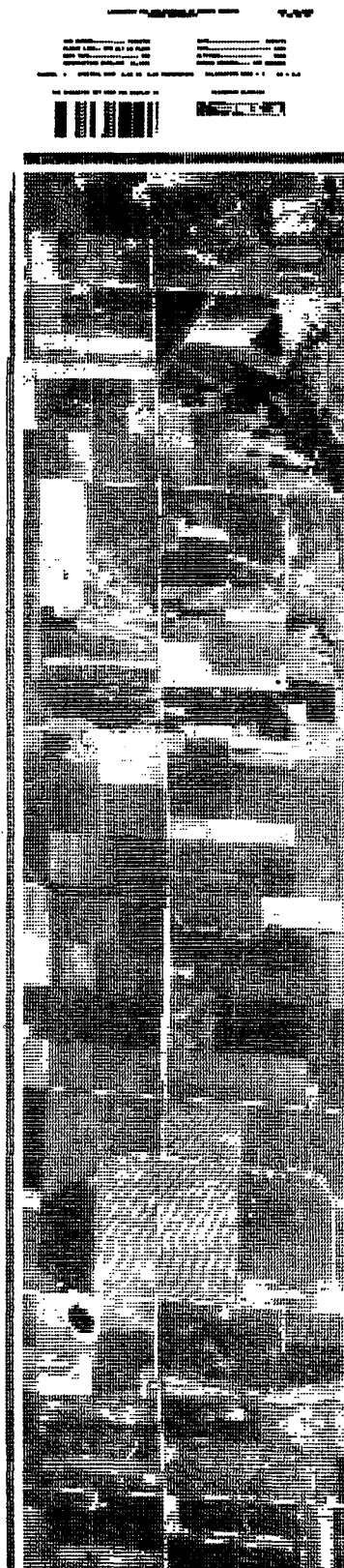
Further work is needed to evaluate and optimize the algorithm. Once satisfactory performance is achieved the output of the CBA must be transferred to a field classification algorithm to achieve the initial intended purpose of the CBA. Classification of the fields could be performed as soon as the fields are closed (completed) or a field output definition could be made and classification performed later. One way this could be accomplished is for the CBA to write a border tape with the fields written in a format easily readable by a per field classifier program.

The processing rate for the present program on an IBM System 360 Model 67 is approximately .25 sec of CPU time per image line of 222 samples for 1 channel processing and .44 sec per line for three channel processing. The flightlines illustrated averaged 770 lines thus the three channel CBA processing time averaged 339 seconds CPU time. Processing time is not of major concern at this stage since quantitative evaluation of the algorithm is not yet achieved.

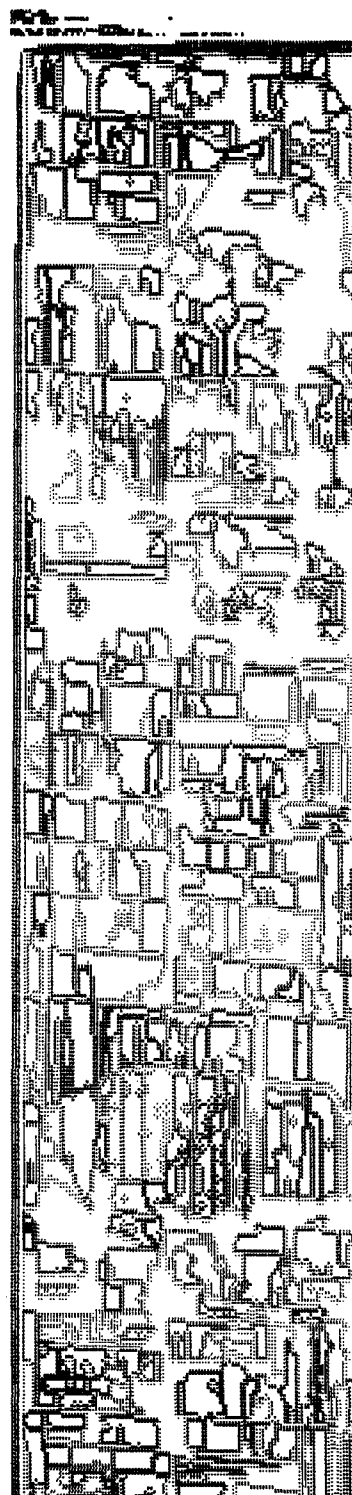
The close cooperation of the IBM Houston Scientific Center and the LARS Purdue organizations was instrumental in achieving the results obtained from this joint study. It is hoped that this document will serve as stimulus to further work on the problems discussed in this report and in the interim report.

References

1. Rosenfeld, A., "Picture Processing by Computer", Academic Press, New York, 1969.
2. Anuta, P. E., "Spatial Registration of Multispectral and Multi-temporal Digital Imagery Using Fast Fourier Transform Techniques", IEEE Transactions on Geoscience Electronics, Vol. GE-8, No. 4, October, 1970.
3. Wacker, A. G., Landgrebe, D. A., "Boundaries in Multispectral Imagery by Clustering", Proceedings of the 9th IEEE Symposium on Adaptive Processes, University of Texas, Austin, December 7 - 9, 1970.
4. Rodd, E. M., "Closed Boundary Field Selection in Multispectral Digital Images", IBM Publication No. 320.2420, IBM Houston Scientific Center, January 14, 1972.
5. Ostle, B., "Statistics in Research", Iowa State University Press, Ames, Iowa, 1963.
6. Ready, P. J. Wintz, P. A., Multispectral Data Compression Through Transform Coding and Block Quantization, "PhD Thesis, School of Electrical Engineering, Purdue University, TR-EE 72-2; and LARS Information Note 050572, May 1972.

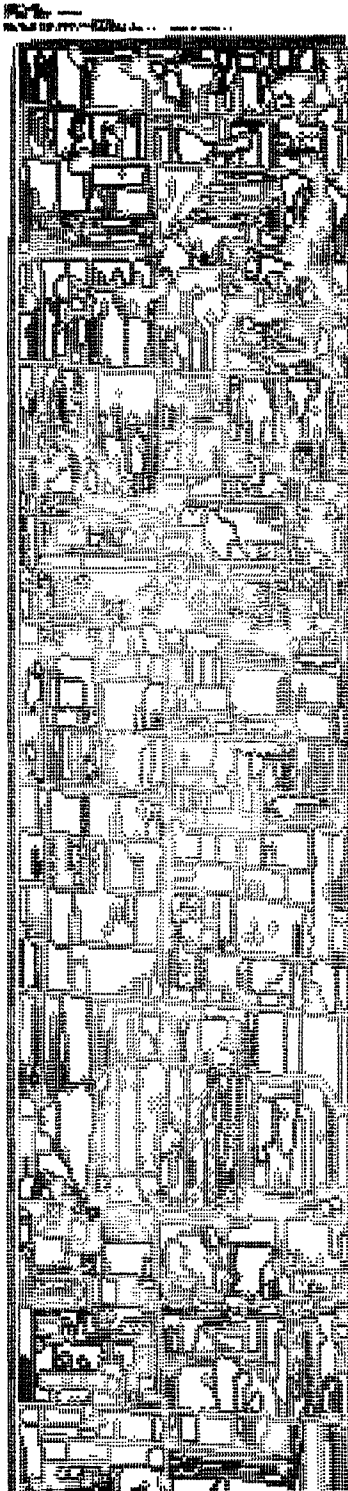


a) Gray Scale Printout

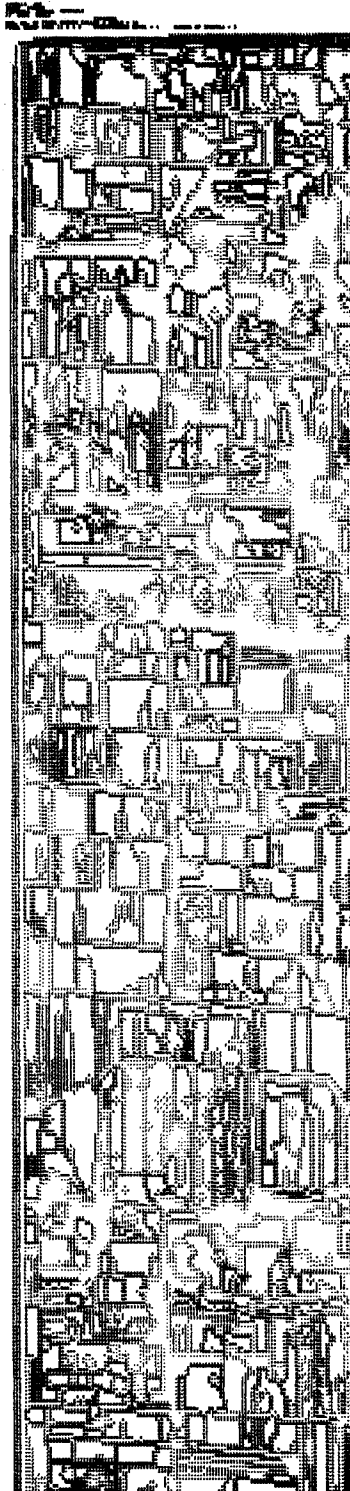


b) CBA Output

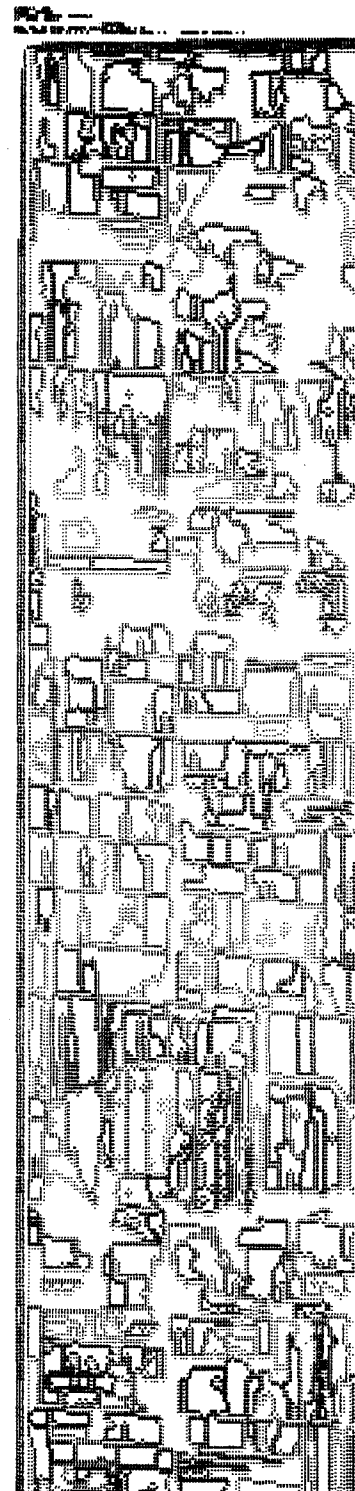
Figure 1. (a) Gray scale line printer image of .58 - .65 micrometer band aircraft scanner data. (b) Closed boundary algorithm output for the scanner data. Parameters: MINFLD = 128, SIGLEV = 4, CHANNELS 4, 6, 8. LARS Run No. 71062701.



MINFLD = 32

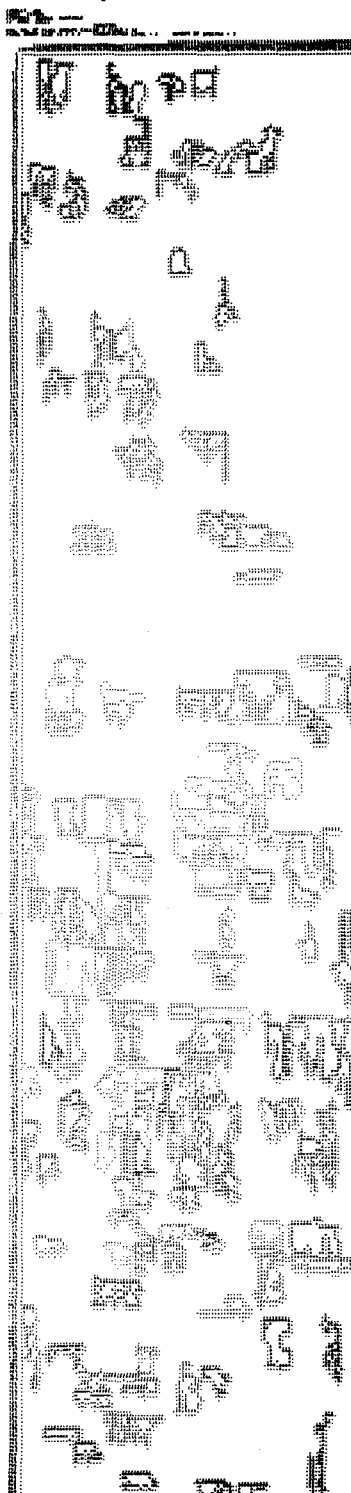


MINFLD = 64

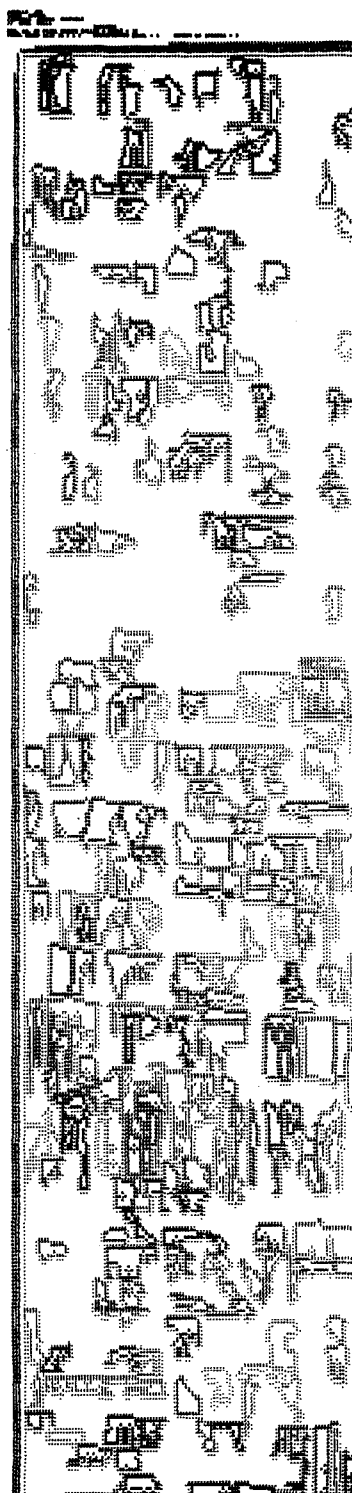


MINFLD = 128

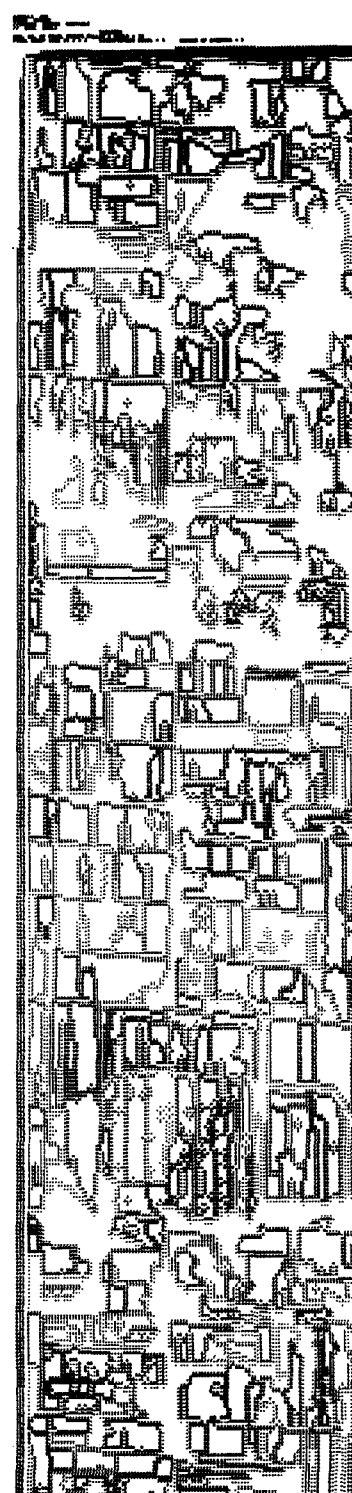
Figure 2. Comparison of the effect of three values of minimum field size on CBA output. Significance Level = 4, Channels 4, 6, 8.



SIGLEV = 2

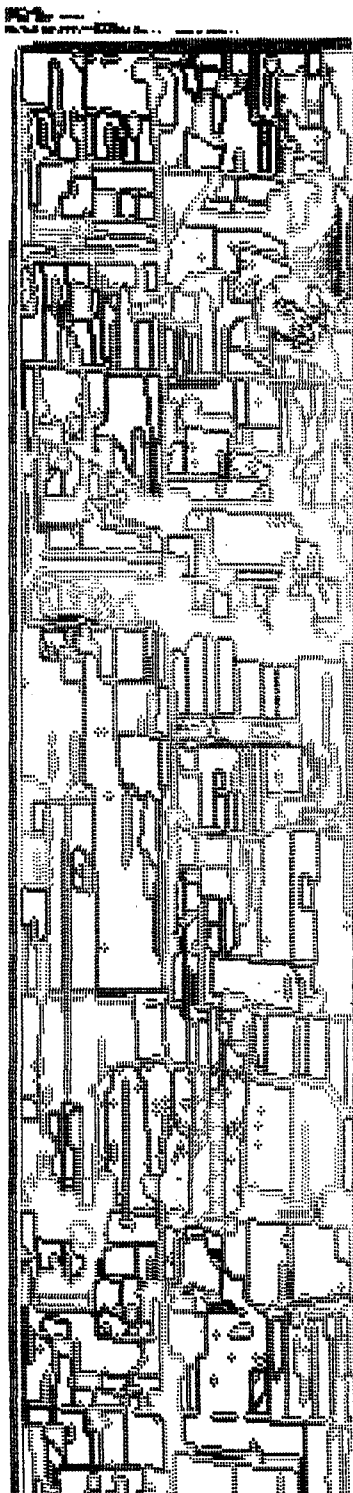


SIGLEV = 3

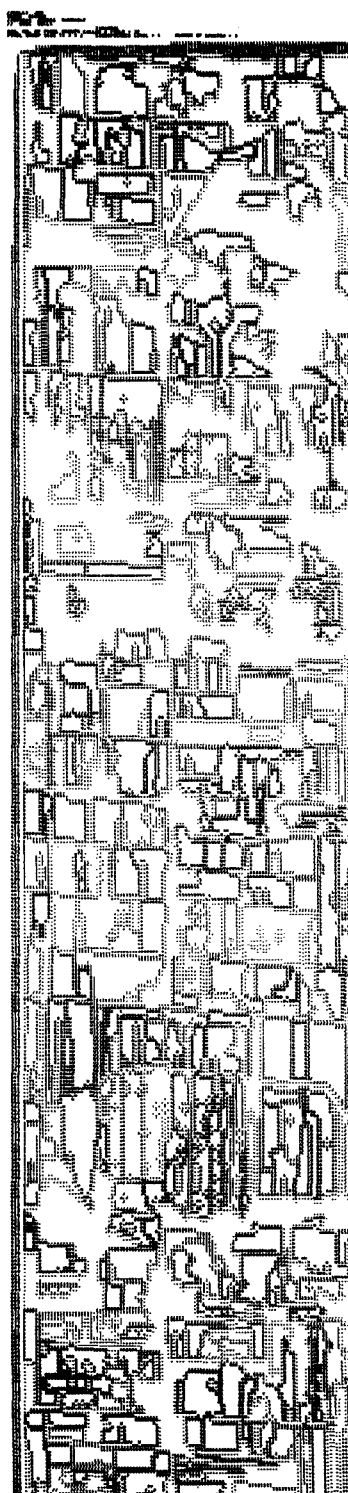


SIGLEV = 4

Figure 3. Comparison of CBA output for three values of significance level. Channels 4, 6, 8 and MINFLD = 128.

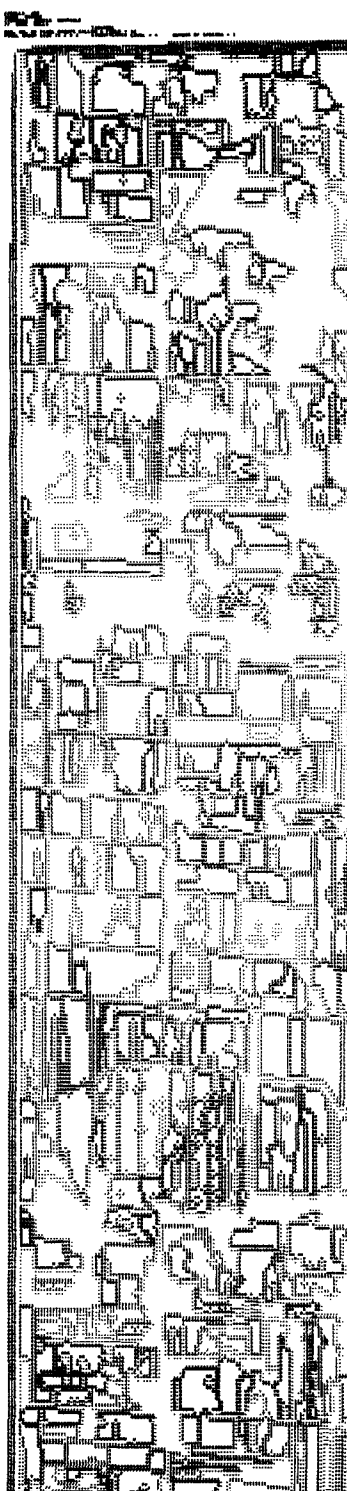


Channel 6

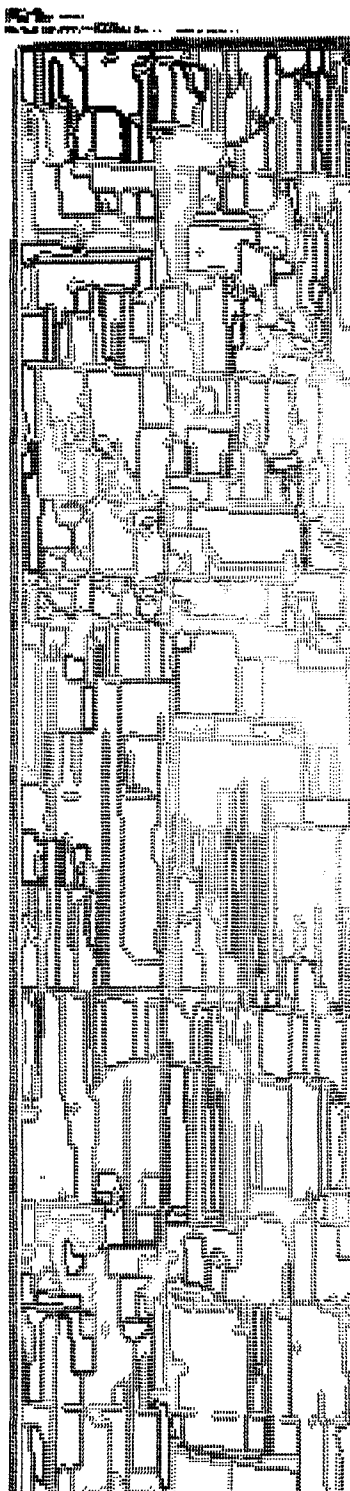


Channels 4, 6, 8

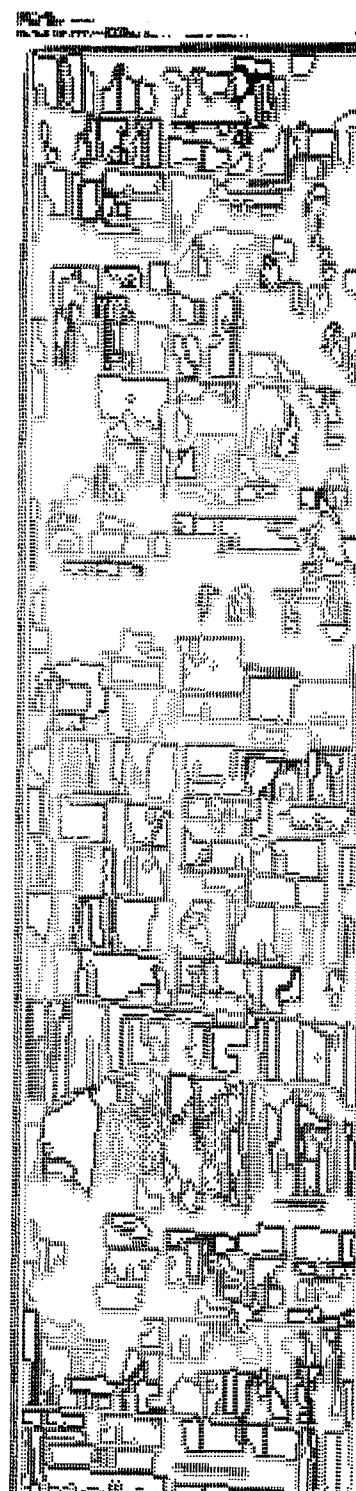
Figure 4. Comparison of CBA output for two sets of channels. Significance level 4 and MINFLD = 128 used.



3 Channels
Untransformed

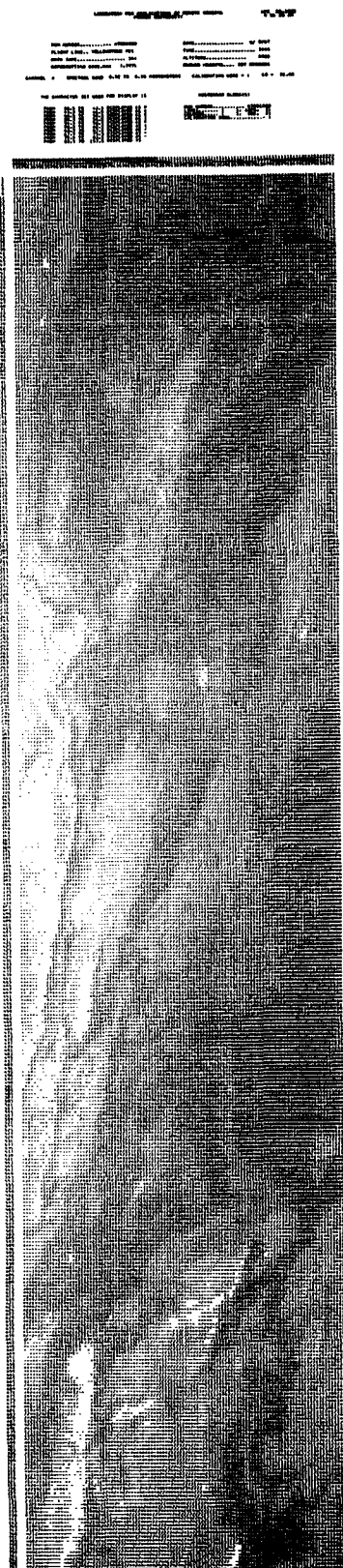


Principal
Component 1

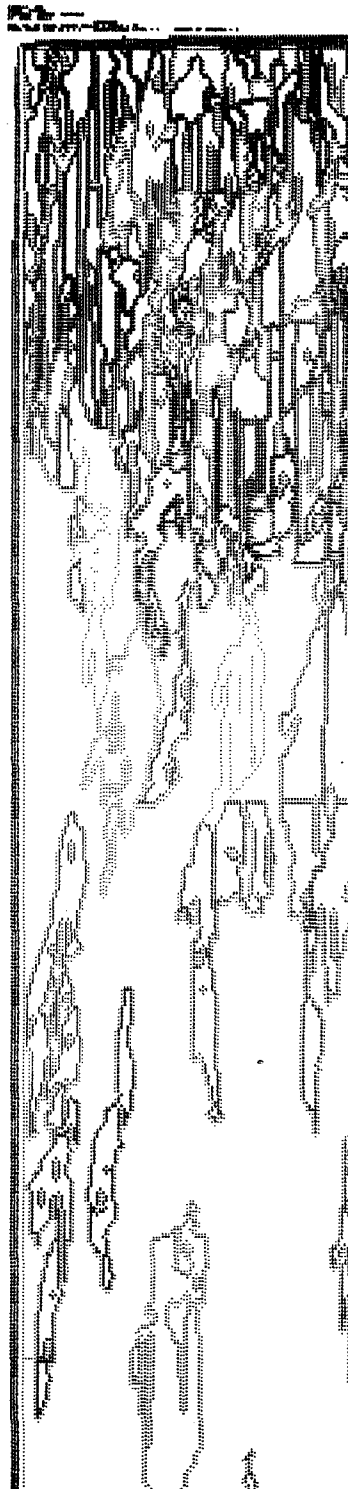


Principal
Components
1,2,3

Figure 5. Comparison of CBA output from unaltered data and principal components data. MINFLD = 128, Significance Level 4.



Gray Scale Printout



CBA Output

Figure 6. Gray scale printout and CBA output for forest and meadow topography in Yellowstone Park, Wyoming. Parameters: MINFLD = 128, Channels 4, 6, 8; SIGLEV = 4.

Appendix I

Fortran Listing of Closed Boundary Finding Algorithm

FORTRAN IV MODEL 44 PS VERSION 3, LEVEL 4 DATE 72215

[illegible]

CEL00010
CEL00020
CEL00030
CEL00040
CEL00050
CEL00060
CEL00070
CEL00080
CEL00090
CEL00100
CEL00110
CEL00120
CEL00130
CEL00140
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CEL00160
CEL00170
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CEL00200
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CEL00960
CEL00970
CEL00980
CEL00990

FORTRAN IV MODEL 44 PS VERSION 3, LEVEL 4 DATE 72215

```

0103      170 IF (ASIN(JMW)) G3 TO 190
0104          ASTN(JMW) = .TRUE.
0105          CALL SET
0106          FSR1(IPLD) = JLINE+1
0107          RWFLD(JMW) = IPLD
0108          180 = JN-PXGR
0109
0110 C      IF (ASIN(JMW)) G3 TO 190
0111          JS = JNR
0112          CHECK AGAINST ONE BEHIND IF IT IS NOT ASSIGNED.
0113 C      IF (.NOT. SAME) GO TO 170
0114          IF A NEW FIELD GO BACK AND ASSIGN.
0115
0116          ASIN(JMW) = .TRUE.
0117          RWFLD(JMW) = IPLD
0118          CALL ADDFIELD(JMW)
0119 C      NOW GO CHECK NEXT GROUP BACK ACROSS.
0120          GO TO 180
0121          190 JN = JN-PXGR
0122          IF JN = 0, WE GO TO 170
0123          200 CALL PRINT
0124          DO 220 = 1, NL2, PXGM
0125              OPENOLD(RWFLD(JMW)) = .FALSE.
0126              CLOSE(RWFLD(JMW))
0127          220 RWFLD IS MOVED TO OLDROW FOR COMPARISONS FROM NEXT ROW.
0128              GO DOWN NOW IN ORDER TO CHECK WHICH VECTORS OF AFLD ARE OPEN ON
0129              LAST ROW AND CLOSE INDICATES WHICH VECTORS ARE CLOSED
0130              ON CURRENT ROW.
0131
0132 C      DO 230 ICLOSE = 1, 250
0133          IF (OPEN(ICLOSE)) .AND. CLOSE(ICLOSE) CALL CLSTK
0134          OPEN(ICLOSE) = .FALSE.
0135          230 CLOSE(ICLOSE) = .TRUE.
0136          FOR ALL THE VECTORS JUST ADDED, CLASSIFICATION IS PERFORMED
0137          THEY OPEN AND CLOSE ARE INITIALIZED FOR THE NEXT ROW.
0138
0139          PRINT1 IS CALLED TO PRINT RESULTS OF 50 ROWS.
0140          PRINT1 IS THE FIRST 50 ROWS HAVE BEEN PROCESSED
0141          TO PRINT THE FIRST FIFTY ROWS AND THEN AFTER EACH FIFTY ROWS
0142          HAVE BEEN PROCESSED TO PRINT AN ADDITIONAL 50 ROWS.
0143          240 IF JNR-GE. 1000. .AND. MOD(JNR,50) .EQ. 01 CALL PRINT1
0144              JN = JNR-1
0145          250 CONTINUE
0146          JN = JNR+1
0147          THIS CALL TO PRINT1 WILL PRINT RESULTS OF ALL REMAINING
0148          ROWS
0149 C      ATIME = FLDAT((CONTAINEROUT)/100.0
0150          ATIME WILL CONTAIN THE TOTAL CPU TIME) SINCE THE
0151          CALL TO ITIMER IN STATEMENT 1
0152          WRITE (OUT124) ATIME
0153          267 FORMAT ('TIME USED',F8.2,' SECONDS')
0154          STOP
0155          END

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CEL01570
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CEL02120
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0050 020 250 JR = IRL1,IR2,PKGR
0051 CALL PKRDM
0052 C READ IN NEXT ROW OF PIXEL GROUPS.
0053 ASIN(JM) = TRUE
0054 INITIALIZE GROUP PIXEL GROUPS AS ASSIGNED.
0055 JS = JW
0056 C CHECK AGAINST GROUP ABOVE.
0057 IF (L-NOT, SAME) GO TO 160
0058 C PUT GROUP INTO SAME FIELD AS GROUP ABOVE.
0059 ASIN(JM) = TRUE.
0060 NFIELD = OLDVAL(JM)
0061 NFIELD(JM) = NFIELD
0062 CALL ADDINFLD(JM)
0063 IF (JM .EQ. W1) GO TO 160
0064 C CHECK BACK ACROSS FOR UNASSIGNED GROUP.
0065 IF ONE GROUP BACK IS NEW FIELD ASSIGNED, GO TO NEXT GROUP.
0066 JS = JN-PKGR
0067 120 JS = JS-PKGR
0068 CALL PKRDM
0069 C CHECK AGAINST ONE GROUP BACK. IF IT IS DIFFERENT,
0070 TRANSFER TO PROCESSING OF NEXT GROUP.
0071 IF (NOT, SAME) GO TO 160
0072 ASIN(JJ) = TRUE.
0073 NFIELD = OLDVAL(JJ)
0074 NFIELD(JJ) = NFIELD
0075 CALL ADDINFLD(JJ)
0076 JS = JS-PKGR
0077 C CHECK TO SEE IF BACK AT BEGINNING OF ROW.
0078 IF (JS .GE. W1) GO TO 120
0079 GO TO 160
0080 130 JS = JS-PKGR
0081 C SINCE THIS GROUP DIFFERS FROM THE ONE ABOVE, ASK IF THE ONE
0082 BEFORE THIS GROUP DIFFERS IF SO COMPARE TO IT.
0083 IF (ASIN(JM-PKGR)) GO TO 135
0084 IF (NFIELD, W1) GO TO 140
0085 IF ONE ABOVE, IF PROVIDES FOR SPECIAL TREATMENT AT THE END OF A ROW.
0086 GO TO 160
0087 135 CALL ST81
0088 IF (SAME) GO TO 137
0089 IF (JM .EQ. W1) GO TO 140
0090 GO TO 160
0091 C GO TO 160
0092 137 ASIN(JM) = TRUE
0093 FLD = NFIELD(JM-PKGR)
0094 NFIELD(JM) = FLD
0095 CALL ADDINFLD(JM)
0096 GO TO 160
0097 140 CALL ST80
0098 FLD = FLD-1
0099 FPD(FLD) = CODE FOR NEW FIELD AT END OF ROW.
0100 ASIN(JM) = TRUE.
0101 NFIELD(JM) = FLD
0102 IF ONE BACK, JS ASSIGNED NO NEED TO COMPARE IT.
0103 JS = JW-PKGR
0104 CALL ST81
0105 IF (SAME) GO TO 160
0106 LOOK TO CHECK BACK ACROSS.
0107 ASIN(JJ) = TRUE
0108 NFIELD(JJ) = FLD
0109 CALL ADDINFLD(JJ)
0110 IF (ASIN(JM)) GO TO 160
0111 IF (JM .GE. W1) GO TO 160
0112 160 CONTINUE
0113 C FOLLOWING IS GOING BACK THROUGH ROW TO PICK UP ANY GROUPS
0114 NOT YET ASSIGNED AND CALLING THEN NEW FIELDS.
0115 JM = W1

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0001 SUBROUTINE PGKRW
0002     READS IN A NEW ROW OF PIXEL GROUPS AND COMPUTES THE SJMS AND SUMS
0003     OF SQUARED VALUES OF EACH PIXEL GROUP
0004     IMPLICIT INTEGER*4 (I-Z)
0005     INTEGER*4 I,J,K,L,N,M,N1,N2,N3,N4,N5,N6,N7,N8,N9,N10,N11,N12,N13,N14,N15,N16,N17,N18,N19,N20,N21,N22,N23,N24,N25,N26,N27,N28,N29,N30,N31,N32,N33,N34,N35,N36,N37,N38,N39,N40,N41,N42,N43,N44,N45,N46,N47,N48,N49,N50,N51,N52,N53,N54,N55,N56,N57,N58,N59,N60,N61,N62,N63,N64,N65,N66,N67,N68,N69,N70,N71,N72,N73,N74,N75,N76,N77,N78,N79,N80,N81,N82,N83,N84,N85,N86,N87,N88,N89,N90,N91,N92,N93,N94,N95,N96,N97,N98,N99,N100,N101,N102,N103,N104,N105,N106,N107,N108,N109,N110,N111,N112,N113,N114,N115,N116,N117,N118,N119,N120,N121,N122,N123,N124,N125,N126,N127,N128,N129,N130,N131,N132,N133,N134,N135,N136,N137,N138,N139,N140,N141,N142,N143,N144,N145,N146,N147,N148,N149,N150,N151,N152,N153,N154,N155,N156,N157,N158,N159,N160,N161,N162,N163,N164,N165,N166,N167,N168,N169,N170,N171,N172,N173,N174,N175,N176,N177,N178,N179,N180,N181,N182,N183,N184,N185,N186,N187,N188,N189,N190,N191,N192,N193,N194,N195,N196,N197,N198,N199,N200,N201,N202,N203,N204,N205,N206,N207,N208,N209,N210,N211,N212,N213,N214,N215,N216,N217,N218,N219,N220,N221,N222,N223,N224,N225,N226,N227,N228,N229,N230,N231,N232,N233,N234,N235,N236,N237,N238,N239,N240,N241,N242,N243,N244,N245,N246,N247,N248,N249,N250,N251,N252,N253,N254,N255,N256,N257,N258,N259,N260,N261,N262,N263,N264,N265,N266,N267,N268,N269,N270,N271,N272,N273,N274,N275,N276,N277,N278,N279,N280,N281,N282,N283,N284,N285,N286,N287,N288,N289,N290,N291,N292,N293,N294,N295,N296,N297,N298,N299,N300,N301,N302,N303,N304,N305,N306,N307,N308,N309,N310,N311,N312,N313,N314,N315,N316,N317,N318,N319,N320,N321,N322,N323,N324,N325,N326,N327,N328,N329,N330,N331,N332,N333,N334,N335,N336,N337,N338,N339,N340,N341,N342,N343,N344,N345,N346,N347,N348,N349,N350,N351,N352,N353,N354,N355,N356,N357,N358,N359,N360,N361,N362,N363,N364,N365,N366,N367,N368,N369,N370,N371,N372,N373,N374,N375,N376,N377,N378,N379,N380,N381,N382,N383,N384,N385,N386,N387,N388,N389,N390,N391,N392,N393,N394,N395,N396,N397,N398,N399,N400,N401,N402,N403,N404,N405,N406,N407,N408,N409,N410,N411,N412,N413,N414,N415,N416,N417,N418,N419,N420,N421,N422,N423,N424,N425,N426,N427,N428,N429,N430,N431,N432,N433,N434,N435,N436,N437,N438,N439,N440,N441,N442,N443,N444,N445,N446,N447,N448,N449,N450,N451,N452,N453,N454,N455,N456,N457,N458,N459,N460,N461,N462,N463,N464,N465,N466,N467,N468,N469,N470,N471,N472,N473,N474,N475,N476,N477,N478,N479,N480,N481,N482,N483,N484,N485,N486,N487,N488,N489,N490,N491,N492,N493,N494,N495,N496,N497,N498,N499,N500,N501,N502,N503,N504,N505,N506,N507,N508,N509,N510,N511,N512,N513,N514,N515,N516,N517,N518,N519,N520,N521,N522,N523,N524,N525,N526,N527,N528,N529,N530,N531,N532,N533,N534,N535,N536,N537,N538,N539,N540,N541,N542,N543,N544,N545,N546,N547,N548,N549,N550,N551,N552,N553,N554,N555,N556,N557,N558,N559,N560,N561,N562,N563,N564,N565,N566,N567,N568,N569,N570,N571,N572,N573,N574,N575,N576,N577,N578,N579,N580,N581,N582,N583,N584,N585,N586,N587,N588,N589,N590,N591,N592,N593,N594,N595,N596,N597,N598,N599,N600,N601,N602,N603,N604,N605,N606,N607,N608,N609,N610,N611,N612,N613,N614,N615,N616,N617,N618,N619,N620,N621,N622,N623,N624,N625,N626,N627,N628,N629,N630,N631,N632,N633,N634,N635,N636,N637,N638,N639,N640,N641,N642,N643,N644,N645,N646,N647,N648,N649,N650,N651,N652,N653,N654,N655,N656,N657,N658,N659,N660,N661,N662,N663,N664,N665,N666,N667,N668,N669,N670,N671,N672,N673,N674,N675,N676,N677,N678,N679,N680,N681,N682,N683,N684,N685,N686,N687,N688,N689,N690,N691,N692,N693,N694,N695,N696,N697,N698,N699,N700,N701,N702,N703,N704,N705,N706,N707,N708,N709,N710,N711,N712,N713,N714,N715,N716,N717,N718,N719,N720,N721,N722,N723,N724,N725,N726,N727,N728,N729,N730,N731,N732,N733,N734,N735,N736,N737,N738,N739,N740,N741,N742,N743,N744,N745,N746,N747,N748,N749,N750,N751,N752,N753,N754,N755,N756,N757,N758,N759,N760,N761,N762,N763,N764,N765,N766,N767,N768,N769,N770,N771,N772,N773,N774,N775,N776,N777,N778,N779,N780,N781,N782,N783,N784,N785,N786,N787,N788,N789,N790,N791,N792,N793,N794,N795,N796,N797,N798,N799,N800,N801,N802,N803,N804,N805,N806,N807,N808,N809,N810,N811,N812,N813,N814,N815,N816,N817,N818,N819,N820,N821,N822,N823,N824,N825,N826,N827,N828,N829,N830,N831,N832,N833,N834,N835,N836,N837,N838,N839,N840,N841,N842,N843,N844,N845,N846,N847,N848,N849,N850,N851,N852,N853,N854,N855,N856,N857,N858,N859,N860,N861,N862,N863,N864,N865,N866,N867,N868,N869,N870,N871,N872,N873,N874,N875,N876,N877,N878,N879,N880,N881,N882,N883,N884,N885,N886,N887,N888,N889,N890,N891,N892,N893,N894,N895,N896,N897,N898,N899,N900,N901,N902,N903,N904,N905,N906,N907,N908,N909,N910,N911,N912,N913,N914,N915,N916,N917,N918,N919,N920,N921,N922,N923,N924,N925,N926,N927,N928,N929,N930,N931,N932,N933,N934,N935,N936,N937,N938,N939,N940,N941,N942,N943,N944,N945,N946,N947,N948,N949,N950,N951,N952,N953,N954,N955,N956,N957,N958,N959,N960,N961,N962,N963,N964,N965,N966,N967,N968,N969,N970,N971,N972,N973,N974,N975,N976,N977,N978,N979,N980,N981,N982,N983,N984,N985,N986,N987,N988,N989,N990,N991,N992,N993,N994,N995,N996,N997,N998,N999,N1000,N1001,N1002,N1003,N1004,N1005,N1006,N1007,N1008,N1009,N1010,N1011,N1012,N1013,N1014,N1015,N1016,N1017,N1018,N1019,N1020,N1021,N1022,N1023,N1024
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PGR00795
PGR00800
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[illegible]

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0001      FUNCTION I(TIMER (J))
0002      I(TIMER) = 0
0003      RETURN
0004      END

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[illegible][illegible]

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0035      23 CONTINUE
0036      30 IDT = NUNB*
0037      IF (IDT - GT. 30) IDT = 30
0038      IF (IDT - LT. 40) IDT = 40
0039      IF (IDT - LT. 60) IDT = 60
0040      IF (IDT - LT. 80) IDT = 80
0041      IF (IDT - LT. 120) IDT = 120
0042      IDT = IDT + 1
0043      IDT = IDT + 1
0044      IDT = IDT + 1
0045      39 IDT = LOGIC GETS THE CORRECT INDEX FOR THE NUMBER OF DEGREES
0046      OF FREEDOM
0047      DO 50 N5 = 1, NCHAN
0048      40 IF TABSTAT(N5, ATSTATAT(IDT, SIGLEV)) SAME = .FALSE.
0049      IF THE NO. OF TABS (N5) GREATER THAN THE CRITERION VALUE
0050      FOR THE TWO SAMPLES, THEN THE NULL HYPOTHESIS THAT
0051      THE TWO SAMPLES ARE THE SAME IS REJECTED.
0052      RETURN
0053      END

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TU000790
 TU000800
 TU000810
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 TU000900
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 TU000960
 TU000970
 TU000980
 TU000990

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[illegible]

PR1000790
PR1000800
PR1000810
PR1000820
PR1000830
PR1000840
PR1000850
PR1000860
PR1000870
PR1000880
PR1000890
PR1000900
PR1000910
PR1000920
PR1000930
PR1000940
PR1000950
PR1000960
PR1000970
PR1000980
PR1000990
PR1010000
PR1010010
PR1010020
PR1010030
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PR1010050
PR1010060
PR1010070
PR1010080
PR1010090
PR1010100
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PR1010240
PR1010250
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PR1010270
PR1010280

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[illegible]

PRI 00010
 PRI 00020
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 PRI 00040
 PRI 00050
 PRI 00060
 PRI 00070
 PRI 00080
 PRI 00090
 PRI 00100
 PRI 00110
 PRI 00120
 PRI 00130
 PRI 00140
 PRI 00150
 PRI 00160
 PRI 00170
 PRI 00180
 PRI 00190
 PRI 00200
 PRI 00210
 PRI 00220
 PRI 00230
 PRI 00240
 PRI 00250
 PRI 00260
 PRI 00270
 PRI 00280
 PRI 00290
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 PRI 00370
 PRI 00380
 PRI 00390
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 PRI 00670
 PRI 00680
 PRI 00690
 PRI 00700
 PRI 00710
 PRI 00720
 PRI 00730
 PRI 00740
 PRI 00750
 PRI 00760
 PRI 00770
 PRI 00780

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0001 SUBROUTINE GETPRM
0002 GETPRM READS IN VARIOUS PARAMETERS. THE FIRST IS THE INPUT
0003 UNIT NUMBER FROM WHICH THE REMAINING PARAMETERS ARE
0004 TO BE READ.
0005 THEN COME THE TITLE, PIXEL GROUP SIZE, RUNS AND
0006 COLUMNS TO BE PROCESSED, SIGNIFICANCE LEVEL, MINIMUM FIELD
0007 LINE, NUMBER OF SPECIES AND THE UNIT NUMBER
0008 TO WHICH THE OUTPUT IS TO BE WRITTEN. OTHER INITIALIZATION
0009 FUNCTIONS ARE ALSO PERFORMED.
0010 IMPLICIT INTEGER*2 (E-Z)
0011 LOGICAL
0012 COMMON /INT/ I(12), J(4), ASUM(250,4), ASO(250,4), AT(4),
0013 AFID(250), APGR(1), AR(10), APGR_OUT(1), JNK(5), NS(1),
0014 PGR(250), LASTR(130), SPI(130,10), PAGR, PGRSI, NCHAN,
0015 ROWS(1), COLS(1), SIGLEV, MAX_UV,
0016 TOP, RESLEV, IRL1, IRL2, IRL3, PCLAS, PWIDE, NEXT, JLINE
0017 3 ROWS(1), COLS(1), IRL1, IRL2, IRL3, PCLAS, PWIDE, NEXT, JLINE
0018 INTEGER*4 I, J, RUNNUM, ERRGRN
0019 COMMON /C/ C(1), C2(1), C3(1), C4(1), C5(1), C6(1), C7(1),
0020 DATA AT(1), JNK(1), TOP(1), RUNNUM, RESLEV(130)
0021
0022 C
0023 5 FORMAT (1X,16F10.3, 1X)
0024 READ (IN,16)
0025 IF (IN .EQ. 15) WRITE (15,6)
0026 6 FORMAT (1X,10I10,1F10.3)
0027 READ (IN,7) IRL1,IRL2,IRL3,IRL4
0028 7 FORMAT (4A4)
0029 IF (IN .EQ. 15) WRITE (15,10)
0030 10 FORMAT (1X,10GROUP SIZE, 1X)
0031 READ (IN,11) PGR
0032 IF (IN .EQ. 15) WRITE (15,11)
0033 11 FORMAT (1X,10F10.3)
0034 READ (IN,12) ROWS(1), COLS(1)
0035 12 FORMAT (1X,10F10.3)
0036 IF (IN .EQ. 15) WRITE (15,14)
0037 14 FORMAT (1X,10F10.3)
0038 READ (IN,13) SIGLEV
0039 13 FORMAT (1X,10F10.3)
0040
0041 C
0042 IF (IN .EQ. 15) WRITE (15,60)
0043 60 FORMAT (1X,10F10.3)
0044 READ (IN,61) NPSIZE
0045 61 FORMAT (1X,10F10.3)
0046 NPS = N2-ROUND((R2-R1+1)*PGR*0)
0047 NPS = N2-ROUND((R2-R1+1)*PGR*0)
0048 DO I=1,NPS
0049   DO J=1,PGR
0050     IF (IN .EQ. 15) WRITE (15,62)
0051     62 FORMAT (1X,10F10.3)
0052     READ (IN,63) NCHAN
0053     63 FORMAT (1X,10F10.3)
0054     IF (IN .EQ. 15) WRITE (15,64)
0055     64 FORMAT (1X,10F10.3)
0056     IF (IN .EQ. 15) WRITE (15,65)
0057     65 FORMAT (1X,10F10.3)
0058     IF (IN .EQ. 15) WRITE (15,66)
0059     66 FORMAT (1X,10F10.3)
0060     IF (IN .EQ. 15) WRITE (15,67)
0061     67 FORMAT (1X,10F10.3)
0062     IF (IN .EQ. 15) WRITE (15,68)
0063     68 FORMAT (1X,10F10.3)
0064     IF (IN .EQ. 15) WRITE (15,69)
0065     69 FORMAT (1X,10F10.3)
0066     IF (IN .EQ. 15) WRITE (15,70)
0067     70 FORMAT (1X,10F10.3)
0068     IF (IN .EQ. 15) WRITE (15,71)
0069     71 FORMAT (1X,10F10.3)
0070     IF (IN .EQ. 15) WRITE (15,72)
0071     72 FORMAT (1X,10F10.3)
0072     IF (IN .EQ. 15) WRITE (15,73)
0073     73 FORMAT (1X,10F10.3)
0074     IF (IN .EQ. 15) WRITE (15,74)
0075     74 FORMAT (1X,10F10.3)
0076     IF (IN .EQ. 15) WRITE (15,75)
0077     75 FORMAT (1X,10F10.3)
0078     IF (IN .EQ. 15) WRITE (15,76)
0079     76 FORMAT (1X,10F10.3)
0080     IF (IN .EQ. 15) WRITE (15,77)
0081     77 FORMAT (1X,10F10.3)
0082     IF (IN .EQ. 15) WRITE (15,78)
0083     78 FORMAT (1X,10F10.3)
0084     IF (IN .EQ. 15) WRITE (15,79)
0085     79 FORMAT (1X,10F10.3)
0086     IF (IN .EQ. 15) WRITE (15,80)
0087     80 FORMAT (1X,10F10.3)
0088     IF (IN .EQ. 15) WRITE (15,81)
0089     81 FORMAT (1X,10F10.3)
0090     IF (IN .EQ. 15) WRITE (15,82)
0091     82 FORMAT (1X,10F10.3)
0092     IF (IN .EQ. 15) WRITE (15,83)
0093     83 FORMAT (1X,10F10.3)
0094     IF (IN .EQ. 15) WRITE (15,84)
0095     84 FORMAT (1X,10F10.3)
0096     IF (IN .EQ. 15) WRITE (15,85)
0097     85 FORMAT (1X,10F10.3)
0098     IF (IN .EQ. 15) WRITE (15,86)
0099     86 FORMAT (1X,10F10.3)
0100     IF (IN .EQ. 15) WRITE (15,87)
0101     87 FORMAT (1X,10F10.3)
0102     IF (IN .EQ. 15) WRITE (15,88)
0103     88 FORMAT (1X,10F10.3)
0104     IF (IN .EQ. 15) WRITE (15,89)
0105     89 FORMAT (1X,10F10.3)
0106     IF (IN .EQ. 15) WRITE (15,90)
0107     90 FORMAT (1X,10F10.3)
0108     IF (IN .EQ. 15) WRITE (15,91)
0109     91 FORMAT (1X,10F10.3)
0110     IF (IN .EQ. 15) WRITE (15,92)
0111     92 FORMAT (1X,10F10.3)
0112     IF (IN .EQ. 15) WRITE (15,93)
0113     93 FORMAT (1X,10F10.3)
0114     IF (IN .EQ. 15) WRITE (15,94)
0115     94 FORMAT (1X,10F10.3)
0116     IF (IN .EQ. 15) WRITE (15,95)
0117     95 FORMAT (1X,10F10.3)
0118     IF (IN .EQ. 15) WRITE (15,96)
0119     96 FORMAT (1X,10F10.3)
0120     IF (IN .EQ. 15) WRITE (15,97)
0121     97 FORMAT (1X,10F10.3)
0122     IF (IN .EQ. 15) WRITE (15,98)
0123     98 FORMAT (1X,10F10.3)
0124     IF (IN .EQ. 15) WRITE (15,99)
0125     99 FORMAT (1X,10F10.3)
0126     IF (IN .EQ. 15) WRITE (15,100)
0127     100 FORMAT (1X,10F10.3)
0128     IF (IN .EQ. 15) WRITE (15,101)
0129     101 FORMAT (1X,10F10.3)
0130     IF (IN .EQ. 15) WRITE (15,102)
0131     102 FORMAT (1X,10F10.3)
0132     IF (IN .EQ. 15) WRITE (15,103)
0133     103 FORMAT (1X,10F10.3)
0134     IF (IN .EQ. 15) WRITE (15,104)
0135     104 FORMAT (1X,10F10.3)
0136     IF (IN .EQ. 15) WRITE (15,105)
0137     105 FORMAT (1X,10F10.3)
0138     IF (IN .EQ. 15) WRITE (15,106)
0139     106 FORMAT (1X,10F10.3)
0140     IF (IN .EQ. 15) WRITE (15,107)
0141     107 FORMAT (1X,10F10.3)
0142     IF (IN .EQ. 15) WRITE (15,108)
0143     108 FORMAT (1X,10F10.3)
0144     IF (IN .EQ. 15) WRITE (15,109)
0145     109 FORMAT (1X,10F10.3)
0146     IF (IN .EQ. 15) WRITE (15,110)
0147     110 FORMAT (1X,10F10.3)
0148     IF (IN .EQ. 15) WRITE (15,111)
0149     111 FORMAT (1X,10F10.3)
0150     IF (IN .EQ. 15) WRITE (15,112)
0151     112 FORMAT (1X,10F10.3)
0152     IF (IN .EQ. 15) WRITE (15,113)
0153     113 FORMAT (1X,10F10.3)
0154     IF (IN .EQ. 15) WRITE (15,114)
0155     114 FORMAT (1X,10F10.3)
0156     IF (IN .EQ. 15) WRITE (15,115)
0157     115 FORMAT (1X,10F10.3)
0158     IF (IN .EQ. 15) WRITE (15,116)
0159     116 FORMAT (1X,10F10.3)
0160     IF (IN .EQ. 15) WRITE (15,117)
0161     117 FORMAT (1X,10F10.3)
0162     IF (IN .EQ. 15) WRITE (15,118)
0163     118 FORMAT (1X,10F10.3)
0164     IF (IN .EQ. 15) WRITE (15,119)
0165     119 FORMAT (1X,10F10.3)
0166     IF (IN .EQ. 15) WRITE (15,120)
0167     120 FORMAT (1X,10F10.3)
0168     IF (IN .EQ. 15) WRITE (15,121)
0169     121 FORMAT (1X,10F10.3)
0170     IF (IN .EQ. 15) WRITE (15,122)
0171     122 FORMAT (1X,10F10.3)
0172     IF (IN .EQ. 15) WRITE (15,123)
0173     123 FORMAT (1X,10F10.3)
0174     IF (IN .EQ. 15) WRITE (15,124)
0175     124 FORMAT (1X,10F10.3)
0176     IF (IN .EQ. 15) WRITE (15,125)
0177     125 FORMAT (1X,10F10.3)
0178     IF (IN .EQ. 15) WRITE (15,126)
0179     126 FORMAT (1X,10F10.3)
0180     IF (IN .EQ. 15) WRITE (15,127)
0181     127 FORMAT (1X,10F10.3)
0182     IF (IN .EQ. 15) WRITE (15,128)

```

GET 000110
GET 000200
GET 000300
GET 000400
GET 000500
GET 000600
GET 000700
GET 000800
GET 000900
GET 001000
GET 001100
GET 001200
GET 001300
GET 001400
GET 001500
GET 001600
GET 001700
GET 001800
GET 001900
GET 002000
GET 002100
GET 002200
GET 002300
GET 002400
GET 002500
GET 002600
GET 002700
GET 002800
GET 002900
GET 003000
GET 003100
GET 003200
GET 003300
GET 003400
GET 003500
GET 003600
GET 003700
GET 003800
GET 003900
GET 004000
GET 004100
GET 004200
GET 004300
GET 004400
GET 004500
GET 004600
GET 004700
GET 004800
GET 004900
GET 005000
GET 005100
GET 005200
GET 005300
GET 005400
GET 005500
GET 005600
GET 005700
GET 005800
GET 005900
GET 006000
GET 006100
GET 006200
GET 006300
GET 006400
GET 006500
GET 006600
GET 006700
GET 006800
GET 006900
GET 007000
GET 007100
GET 007200
GET 007300

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```

0002 CALL GADRUN (RUNNUM,1,1,0,ERRGRN)
0003 IF (ERRGRN.EQ.0) GO TO 335
0004 WRITE(2,5010) ERRGRN
0005 FORMAT( ' GADRUN ERROR ',12)
0006 PAUSE ' EL BOMBO '
0007 CONTINUE
0008 DO 340 I = 1,30
0009 KSEL(I) = 0
0010 IF (I.NE.1) WRITE(15,350)
0011 FORMAT( ' WHICH CHANNELS (1-12) ' )
0012 READ(1,360) (PIX(I),I=1,NCHAN)
0013 FORMAT( ' 12 ' )
0014 DO 370 I = 1,NCHAN
0015 KSEL(PIX(I)) = 1
0016 RETURN
0017 END

```

GET00780

GET00790

GET00800

GET00820

GET00840

GET00850

GET00860

FLGS	L-CTR	OBJCODE	ADDR	STMT	SOURCE STATEMENT	
				1 *	SHIFT IS A FORTTRAN CALLED ROUTINE TO CONVERT PIXEL DATA TO	XX 00030
				2 *	PROPER INTEGER*2 FORMAT, THE CALLING SEQUENCE IS	XX 00040
				3 *	CALL SHIFT (PIX,DATA,WORDS) WHERE PIX IS AN I*2 VECTOR WHERE	XX 00050
				4 *	THE CONVERTED DATA IS TO BE PLACED, DATA IS A LOGICAL VECTOR	XX 00060
				5 *	WHERE THE DATA COMES IN ONE NUMBER PER BYTE, AND WORDS IS	XX 00070
				6 *	THE NUMBER OF NUMBERS TO BE CONVERTED, WORDS IS AN I*2	XX 00080
				7 *	VARIABLE.	XX 00090
000000	0000	000C	0000C	8	SHIFT	XX 00100
000000	05C0	0000	0000	9	CSECT	XX 00110
000000	05C0	0000	0000	10	STM	XX 00120
000000	05C0	0000	0000	11	BALM	XX 00130
000000	05C0	0000	0000	12	USING	XX 00140
000000	05C0	0000	0000	13	L	XX 00150
000000	05C0	0000	0000	14	L	XX 00160
000012	1855	0000	0000	15	L	XX 00170
000014	18A4	0000	0000	16	SR	XX 00180
000016	1860	C03A	00040	17	SR	XX 00190
000018	4873	0000	00000	18	L	XX 00200
00001E	5870	C03A	00040	19	L	XX 00210
000022	43A2	0000	00000	20	S	XX 00220
000024	40A1	0000	00000	21	SR	XX 00230
000026	4A20	C03E	00044	22	SR	XX 00240
00002E	4A10	C040	00046	23	SR	XX 00250
000032	8756	C01C	00022	24	SR	XX 00260
000034	982C	D01C	0001C	25	SR	XX 00270
000036	42FE	0000	0000C	26	SR	XX 00280
00003E	07FE	0000	0000C	27	SR	XX 00290
000040	00000001	0000	0000C	28	SR	XX 00300
000042	0001	0000	0000C	29	SR	XX 00310
000044	0002	0000	0000C	30	SR	XX 00320
000046	0002	0000	0000C	31	SR	XX 00330
000048	0002	0000	0000C	32	SR	XX 00340
00004A	0002	0000	0000C	33	SR	XX 00350
00004C	0002	0000	0000C	34	SR	XX 00360
00004E	0002	0000	0000C	35	SR	XX 00370
000050	0002	0000	0000C	36	SR	XX 00380
000052	0002	0000	0000C	37	SR	XX 00390
000054	0002	0000	0000C	38	SR	XX 00400
000056	0002	0000	0000C	39	SR	XX 00410
000058	0002	0000	0000C	40	SR	XX 00420
00005A	0002	0000	0000C	41	SR	XX 00430
00005C	0002	0000	0000C	42	SR	XX 00440
00005E	0002	0000	0000C	43	SR	XX 00450
000060	0002	0000	0000C	44	SR	XX 00460
000062	0002	0000	0000C	45	SR	XX 00470
000064	0002	0000	0000C	46	SR	XX 00480
000066	0002	0000	0000C	47	SR	XX 00490
000068	0002	0000	0000C	48	SR	XX 00500
00006A	0002	0000	0000C	49	SR	XX 00510
00006C	0002	0000	0000C	50	SR	XX 00520
00006E	0002	0000	0000C	51	SR	XX 00530
000070	0002	0000	0000C	52	SR	XX 00540
000072	0002	0000	0000C	53	SR	XX 00550
000074	0002	0000	0000C	54	SR	XX 00560
000076	0002	0000	0000C	55	SR	XX 00570
000078	0002	0000	0000C	56	SR	XX 00580
00007A	0002	0000	0000C	57	SR	XX 00590
00007C	0002	0000	0000C	58	SR	XX 00600
00007E	0002	0000	0000C	59	SR	XX 00610
000080	0002	0000	0000C	60	SR	XX 00620
000082	0002	0000	0000C	61	SR	XX 00630
000084	0002	0000	0000C	62	SR	XX 00640
000086	0002	0000	0000C	63	SR	XX 00650
000088	0002	0000	0000C	64	SR	XX 00660
00008A	0002	0000	0000C	65	SR	XX 00670
00008C	0002	0000	0000C	66	SR	XX 00680
00008E	0002	0000	0000C	67	SR	XX 00690
000090	0002	0000	0000C	68	SR	XX 00700
000092	0002	0000	0000C	69	SR	XX 00710
000094	0002	0000	0000C	70	SR	XX 00720
000096	0002	0000	0000C	71	SR	XX 00730
000098	0002	0000	0000C	72	SR	XX 00740
00009A	0002	0000	0000C	73	SR	XX 00750
00009C	0002	0000	0000C	74	SR	XX 00760
00009E	0002	0000	0000C	75	SR	XX 00770
0000A0	0002	0000	0000C	76	SR	XX 00780
0000A2	0002	0000	0000C	77	SR	XX 00790
0000A4	0002	0000	0000C	78	SR	XX 00800
0000A6	0002	0000	0000C	79	SR	XX 00810
0000A8	0002	0000	0000C	80	SR	XX 00820
0000AA	0002	0000	0000C	81	SR	XX 00830
0000AC	0002	0000	0000C	82	SR	XX 00840
0000AE	0002	0000	0000C	83	SR	XX 00850
0000B0	0002	0000	0000C	84	SR	XX 00860
0000B2	0002	0000	0000C	85	SR	XX 00870
0000B4	0002	0000	0000C	86	SR	XX 00880
0000B6	0002	0000	0000C	87	SR	XX 00890
0000B8	0002	0000	0000C	88	SR	XX 00900
0000BA	0002	0000	0000C	89	SR	XX 00910
0000BC	0002	0000	0000C	90	SR	XX 00920
0000BE	0002	0000	0000C	91	SR	XX 00930
0000C0	0002	0000	0000C	92	SR	XX 00940
0000C2	0002	0000	0000C	93	SR	XX 00950
0000C4	0002	0000	0000C	94	SR	XX 00960
0000C6	0002	0000	0000C	95	SR	XX 00970
0000C8	0002	0000	0000C	96	SR	XX 00980
0000CA	0002	0000	0000C	97	SR	XX 00990
0000CC	0002	0000	0000C	98	SR	XX 01000
0000CE	0002	0000	0000C	99	SR	XX 01010
0000D0	0002	0000	0000C	100	SR	XX 01020
0000D2	0002	0000	0000C	101	SR	XX 01030
0000D4	0002	0000	0000C	102	SR	XX 01040
0000D6	0002	0000	0000C	103	SR	XX 01050
0000D8	0002	0000	0000C	104	SR	XX 01060
0000DA	0002	0000	0000C	105	SR	XX 01070
0000DC	0002	0000	0000C	106	SR	XX 01080
0000DE	0002	0000	0000C	107	SR	XX 01090
0000E0	0002	0000	0000C	108	SR	XX 01100
0000E2	0002	0000	0000C	109	SR	XX 01110
0000E4	0002	0000	0000C	110	SR	XX 01120
0000E6	0002	0000	0000C	111	SR	XX 01130
0000E8	0002	0000	0000C	112	SR	XX 01140
0000EA	0002	0000	0000C	113	SR	XX 01150
0000EC	0002	0000	0000C	114	SR	XX 01160
0000EE	0002	0000	0000C	115	SR	XX 01170
0000F0	0002	0000	0000C	116	SR	XX 01180
0000F2	0002	0000	0000C	117	SR	XX 01190
0000F4	0002	0000	0000C	118	SR	XX 01200
0000F6	0002	0000	0000C	119	SR	XX 01210
0000F8	0002	0000	0000C	120	SR	XX 01220
0000FA	0002	0000	0000C	121	SR	XX 01230
0000FC	0002	0000	0000C	122	SR	XX 01240
0000FE	0002	0000	0000C	123	SR	XX 01250
000100	0002	0000	0000C	124	SR	XX 01260
000102	0002	0000	0000C	125	SR	XX 01270
000104	0002	0000	0000C	126	SR	XX 01280
000106	0002	0000	0000C	127	SR	XX 01290
000108	0002	0000	0000C	128	SR	XX 01300
00010A	0002	0000	0000C	129	SR	XX 01310
00010C	0002	0000	0000C	130	SR	XX 01320
00010E	0002	0000	0000C	131	SR	XX 01330
000110	0002	0000	0000C	132	SR	XX 01340
000112	0002	0000	0000C	133	SR	XX 01350
000114	0002	0000	0000C	134	SR	XX 01360
000116	0002	0000	0000C	135	SR	XX 01370
000118	0002	0000	0000C	136	SR	XX 01380
00011A	0002	0000	0000C	137	SR	XX 01390
00011C	0002	0000	0000C	138	SR	XX 01400
00011E	0002	0000	0000C	139	SR	XX 01410
000120	0002	0000	0000C	140	SR	XX 01420
000122	0002	0000	0000C	141	SR	XX 01430
000124	0002	0000	0000C	142	SR	XX 01440
000126	0002	0000	0000C	143	SR	XX 01450
000128	0002	0000	0000C	144	SR	XX 01460
00012A	0002	0000	0000C	145	SR	XX 01470
00012C	0002	0000	0000C	146	SR	XX 01480
00012E	0002	0000	0000C	147	SR	XX 01490
000130	0002	0000	0000C	148	SR	XX 01500
000132	0002	0000	0000C	149	SR	XX 01510
000134	0002	0000	0000C	150	SR	XX 01520
000136	000					

Appendix II

Input - Output and Program Variable Information

The CBA program listed in Appendix I operates under the IBM System 360 Model 44 programming system 44PS. The first section of this appendix describes the necessary control information, the second describes the format of the picture data used by the program and the third section describes the program output. The fourth section describes the program variables.

I.

All of the control parameters are read from cards by the subroutine GETPRM. Below is a list of (1) the format of the cards, (2) the program variable into which the data is read, and (3) an explanation of the parameter.

1. 'RUN IDENTIFIER' Format is 4A4. AFS

This defines an alphabetic identifier for the run. This identifier will be printed at the head of the output.

2. 'GROUP SIZE' Format is I1. PXGR

This requests the value of g, the number of pixels on the side of a pixel group. Thus a pixel group has g^2 pixels.

3. 'ROWS & COLS 4I4' Format is 4I4. R1 R2 W1 W2

This requests which rows and columns of the picture are to be processed. Thus it is not necessary to process starting at the top of the picture or at the left of the picture. The data is of the form: first row, last row, first column, last column. If the specified rows and columns are such that they do not come out on a pixel group boundary, the program will delete sufficient rows

and/or columns to come out even. The maximum number of columns which can be processed is 125/(the group size parameter). There is no restriction on the number of rows.

4. 'SIGLEV' Format is I1. SIGLEV

This is the significance level to be used in the t-test. The values of '1', '2', '3', or '4'. A value of '1' will cause the null hypothesis to be rejected most readily and will thus give the least resolution (and cleanest results).

5. 'MIN SIZE' Format is I2. MFS

This requests the number of pixel groups a field must have in order to engage the per field classifier. If you wish to have per field classification performed on all fields, no matter how small, simply punch '01'. Currently this parameter is used only in the dummy per field classifier.

6. 'NUMBER OF CHANNELS' Format is I1. NCHAN

This requests the number of spectral bands to be used in the picture analysis.

7. 'OUTPUT' Format is I1. OUT

This requests the FORTRAN logical data set number to which results are to be written.

8. 'RUN NUMBER' Format I8.

This is the run number of the data set to be processed.

9. 'CHANNELS' Format NI2

Defines the NCHAN channels to be used.

II.

All use of raw digital picture data is in subroutine PGROW. Thus, to use a different format of picture data, only this subroutine must be altered. Subroutine PGROW is called to read in a row of pixel groups. All that PGROW returns are the values of the sums of the pixels in each group (in each channel) and the sums of the squares of the pixels in each group (in each channel). The actual pixel values are not retained. The sum of the elements of the JS'th pixel group in the row for the NS'th channel is placed in ASO(JW,NS). PGROW has available in the named common /INT2/ the number of channel being processed (in NCHAN), the columns of pixels being considered (in W1 and W2) and the size of a side of a pixel group (in PXGR).

III.

The output consists of a heading giving the title, minimum field size, pixel group size, significance level and number of channels processed; a printout of column numbers; and the body of results. In the body of results, the row number is printed at the left. This is the pixel row, not the pixel group row so that if each pixel group is 2 pixels on a side, these numbers on the left will be 1, 3, 5 etc. The rest of the body of results consists of field identification characters. Only the boundaries of each field are printed. Field identification is assigned by a dummy per field classifier in subroutine CLASS. As each field is

closed, this dummy per field classifier gives a new identifier to it. After all the available characters have been used, it starts over at the beginning of the list of characters.

IV.

Meaning of FORTRAN Variables in the Closed Field Selection Program

This section gives the meaning of the important FORTRAN variables in the Closed Field Selection Program. All the variables discussed below except ASP are in a COMMON block. The program uses COMMON to pass virtually all information from subroutine to subroutine.

Control information

OUT contains the FORTRAN logical unit number to which results are written.

IN contains the FORTRAN logical unit number from which control information is read.

NCHAN contains the number of channels being processed.

PXGR is the value g in the paper. PXGR1 is PXGR-1.

R1 and R2 are the first and last rows of the picture to be processed.

W1 and W2 are the first and last columns of the picture to be processed.

MFS is the minimum field size. This is used only in the dummy per field classifier.

Field statistics

Each vector of ASUM is the vector s in the report for one channel. Each vector of ASQ is the vector q in the report for one channel. Each vector of AFTOT is the vector S in the report for one channel. Each vector of AFS in the vector Q is the report for one channel.

AFLD(1) contains the number of pixel groups in the field whose statistics are contained in the 1'th row of AFTOT and AFS.

AT(1) is computed only in the statistical subroutine (subroutine STU) and contains the value of t for the 1'th channel.

ASP is a local variable in subroutine STU and is the value of Sp^{**2} .

Utilization of field statistics variables

STACK is a stack vector. It is initialized so that STACK(1) = 1. NEXT says which element of the stack to be used next. Each time a field is started, a number is pulled from the stack and this number is the number of the element of AFLD and row of AFTOT and AFS to be used for this field. Also when a new field is started, NEXT is increased by one. Each time a field is closed, a number is returned to the stack. Thus, if a field is closed which was described by the 10'th element of AFLD and the 10'th row of AFTOT and AFS, the number 10 is put into the stack and the value of NEXT is increased by one.

Indication of current processing

JR contains the number of row currently being processed. JR is pixel row, not pixel group row. JR is the DO index on the overall loop over rows. If PXGR is 2, then JR is incremented by two each

time through the loop.

JW contains the number of the column currently being processed. JW is the DO index on the loop passing through the row from left to right.

RWFLD(1) contains the element number of AFLD containing information concerning the 1'th pixel group in the current row. RWFLD is actually the vector f in the report.

OLDRW is the RWFLD from the previous row. It is actually the vector (f) in the report.

Printing of results

SP is the array of results. SP is dimensioned (130,100) so that each vector of SP is a line of printed result. After a row is processed, SP is loaded from the vector RWFLD. When a field is closed, and the field is classified, all entries in SP referring to that field are altered to reflect the classification. To tell whether a field has been classified, the program puts the classification index +256 into SP for each element of SP representing the field just classified. After 100 lines have been processed, 50 lines of results are printed and then after another 50 lines are processed lines 51-100 are printed and so forth. Anytime the print routine is called, results are printed from the first 50 vectors of SP. Then the second fifty vectors of SP are moved to become the first 50. As processing continues, further results are placed in vectors 51-100.

LASTR is a vector of dimension 130. It is positioned in COMMON immediately before SP and is thus logically the zero'th vector of SP. This is done to preserve the last row of results just printed.

This information is needed by the print routine to know whether a boundary was crossed.

FSR(1) contains the number of the first vector of SP which represents the field described by the 1'th element of AFLD. FSR is used after per field classification is done to assist in propagating the field classification index (+256) throughout that part of SP representing the field.

JNR contains the total number of rows of pixel groups processed so far. Each time JNR becomes a multiple of 50 (and is at least 100), 50 lines of results are printed.

JLINE is the counter used to index SP.